

# NAG Toolbox for MATLAB

## f02we

### 1 Purpose

f02we returns all, or part, of the singular value decomposition of a general real matrix.

### 2 Syntax

```
[a, b, q, sv, pt, work, ifail] = f02we(a, b, wantq, wantp, 'm', m, 'n',
n, 'ncolb', ncolb)
```

### 3 Description

The  $m$  by  $n$  matrix  $A$  is factorized as

$$A = QDP^T,$$

where

$$D = \begin{pmatrix} S \\ 0 \end{pmatrix}, \quad m > n,$$

$$D = S, \quad m = n,$$

$$D = (S \ 0), \quad m < n,$$

$Q$  is an  $m$  by  $m$  orthogonal matrix,  $P$  is an  $n$  by  $n$  orthogonal matrix, and  $S$  is a  $\min(m, n)$  by  $\min(m, n)$  diagonal matrix with nonnegative diagonal elements,  $sv_1, sv_2, \dots, sv_{\min(m, n)}$ , ordered such that

$$sv_1 \geq sv_2 \geq \dots \geq sv_{\min(m, n)} \geq 0.$$

The first  $\min(m, n)$  columns of  $Q$  are the left-hand singular vectors of  $A$ , the diagonal elements of  $S$  are the singular values of  $A$  and the first  $\min(m, n)$  columns of  $P$  are the right-hand singular vectors of  $A$ .

Either or both of the left-hand and right-hand singular vectors of  $A$  may be requested and the matrix  $C$  given by

$$C = Q^T B,$$

where  $B$  is an  $m$  by  $ncolb$  given matrix, may also be requested.

f02we obtains the singular value decomposition by first reducing  $A$  to upper triangular form by means of Householder transformations, from the left when  $m \geq n$  and from the right when  $m < n$ . The upper triangular form is then reduced to bidiagonal form by Givens plane rotations and finally the  $QR$  algorithm is used to obtain the singular value decomposition of the bidiagonal form.

Good background descriptions to the singular value decomposition are given in Dongarra *et al.* 1979, Hammarling 1985 and Wilkinson 1978. Note that this function is not based on the LINPACK function SSVDC/DSVDC.

Note that if  $K$  is any orthogonal diagonal matrix so that

$$KK^T = I$$

(so that  $K$  has elements  $+1$  or  $-1$  on the diagonal), then

$$A = (QK)D(PK)^T$$

is also a singular value decomposition of  $A$ .

## 4 References

Dongarra J J, Moler C B, Bunch J R and Stewart G W 1979 *LINPACK Users' Guide* SIAM, Philadelphia  
 Hammarling S 1985 The singular value decomposition in multivariate statistics *SIGNUM Newsl.* **20** (3) 2–25

Wilkinson J H 1978 Singular Value Decomposition – Basic Aspects *Numerical Software – Needs and Availability* (ed D A H Jacobs) Academic Press

## 5 Parameters

### 5.1 Compulsory Input Parameters

1: **a(lda,\*) – double array**

The first dimension of the array **a** must be at least  $\max(1, \mathbf{m})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

The leading  $m$  by  $n$  part of the array **a** must contain the matrix  $A$  whose singular value decomposition is required.

2: **b(ldb,\*) – double array**

The first dimension, **ldb**, of the array **b** must satisfy

if  $\mathbf{ncolb} > 0$ ,  $\mathbf{ldb} \geq \max(1, \mathbf{m})$ ;  
 $\mathbf{ldb} \geq 1$  otherwise.

The second dimension of the array must be at least  $\max(1, \mathbf{ncolb})$

If  $\mathbf{ncolb} > 0$ , the leading  $m$  by  $\mathbf{ncolb}$  part of the array **b** must contain the matrix to be transformed.

3: **wantq – logical scalar**

Must be **true**, if the left-hand singular vectors are required.

If **wantq = false**, the array **q** is not referenced.

4: **wantp – logical scalar**

Must be **true** if the right-hand singular vectors are required.

If **wantp = false**, the array **pt** is not referenced.

### 5.2 Optional Input Parameters

1: **m – int32 scalar**

$m$ , the number of rows of the matrix  $A$ .

*Constraint:*  $\mathbf{m} \geq 0$ .

If  $\mathbf{m} = 0$ , an immediate return is effected

2: **n – int32 scalar**

*Default:* The second dimension of the array **a**.

$n$ , the number of columns of the matrix  $A$ .

*Constraint:*  $\mathbf{n} \geq 0$ .

If  $\mathbf{n} = 0$ , an immediate return is effected

3: **ncolb – int32 scalar**

*Default:* The second dimension of the array **b**.

$ncolb$ , the number of columns of the matrix  $B$ .

If  $ncolb = 0$ , the array  $\mathbf{b}$  is not referenced.

Constraint:  $ncolb \geq 0$ .

### 5.3 Input Parameters Omitted from the MATLAB Interface

$lda$ ,  $ldb$ ,  $ldq$ ,  $ldpt$

### 5.4 Output Parameters

#### 1: $\mathbf{a}(lda,*)$ – double array

The first dimension of the array  $\mathbf{a}$  must be at least  $\max(1, \mathbf{m})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

If  $\mathbf{m} \geq \mathbf{n}$  and  $\mathbf{wantq} = \mathbf{true}$ , the leading  $m$  by  $n$  part of  $\mathbf{a}$  will contain the first  $n$  columns of the orthogonal matrix  $Q$ .

If  $\mathbf{m} < \mathbf{n}$  and  $\mathbf{wantp} = \mathbf{true}$ , the leading  $m$  by  $n$  part of  $\mathbf{a}$  will contain the first  $m$  rows of the orthogonal matrix  $P^T$ .

If  $\mathbf{m} \geq \mathbf{n}$  and  $\mathbf{wantq} = \mathbf{false}$  and  $\mathbf{wantp} = \mathbf{true}$ , the leading  $n$  by  $n$  part of  $\mathbf{a}$  will contain the first  $n$  rows of the orthogonal matrix  $P^T$ .

Otherwise the leading  $m$  by  $n$  part of  $\mathbf{a}$  is used as internal workspace.

#### 2: $\mathbf{b}(ldb,*)$ – double array

The first dimension,  $ldb$ , of the array  $\mathbf{b}$  must satisfy

if  $ncolb > 0$ ,  $ldb \geq \max(1, \mathbf{m})$ ;  
 $ldb \geq 1$  otherwise.

The second dimension of the array must be at least  $\max(1, ncolb)$

Contains the  $m$  by  $ncolb$  matrix  $\mathbf{q}^T \mathbf{b}$ .

#### 3: $\mathbf{q}(ldq,*)$ – double array

The first dimension,  $ldq$ , of the array  $\mathbf{q}$  must satisfy

if  $\mathbf{m} < \mathbf{n}$  and  $\mathbf{wantq} = \mathbf{true}$ ,  $ldq \geq \max(1, \mathbf{m})$ ;  
 $ldq \geq 1$  otherwise.

The second dimension of the array must be at least  $\max(1, \mathbf{m})$

If  $\mathbf{m} < \mathbf{n}$  and  $\mathbf{wantq} = \mathbf{true}$ , the leading  $m$  by  $m$  part of the array  $\mathbf{q}$  will contain the orthogonal matrix  $Q$ . Otherwise the array  $\mathbf{q}$  is not referenced.

#### 4: $\mathbf{sv}(*)$ – double array

**Note:** the dimension of the array  $\mathbf{sv}$  must be at least  $\min(\mathbf{m}, \mathbf{n})$ .

The  $\min(m, n)$  diagonal elements of the matrix  $S$ .

#### 5: $\mathbf{pt}(ldpt,*)$ – double array

The first dimension,  $ldpt$ , of the array  $\mathbf{pt}$  must satisfy

if  $\mathbf{m} \geq \mathbf{n}$  and  $\mathbf{wantq} = \mathbf{true}$  and  $\mathbf{wantp} = \mathbf{true}$ ,  $ldpt \geq \max(1, \mathbf{n})$ ;  
 $ldpt \geq 1$  otherwise.

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

If  $\mathbf{m} \geq \mathbf{n}$  and  $\mathbf{wantq}$  and  $\mathbf{wantp}$  are  $\mathbf{true}$ , the leading  $n$  by  $n$  part of the array  $\mathbf{pt}$  will contain the orthogonal matrix  $P^T$ . Otherwise the array  $\mathbf{pt}$  is not referenced.

6: **work(\*) – double array**

**Note:** the dimension of the array **work** must be at least  $\max(1, lwork)$ , where *lwork* must be as given as follows:

**m**  $\geq$  **n**

**wantq** = **true** and **wantp** = **true**

$$lwork = \max(\mathbf{n}^2 + 5 \times (\mathbf{n} - 1), \mathbf{n} + \mathbf{ncolb}, 4)$$

**wantq** = **true** and **wantp** = **false**

$$lwork = \max(\mathbf{n}^2, \mathbf{ncolb}) + \max(4 \times (\mathbf{n} - 1), 5) + 1$$

**wantq** = **false** and **wantp** = **true**

$$lwork = \max(3 \times (\mathbf{n} - 1), 2) \quad \text{when } \mathbf{ncolb} = 0$$

$$lwork = \max(5 \times (\mathbf{n} - 1), 2) \quad \text{when } \mathbf{ncolb} > 0$$

**wantq** = **false** and **wantp** = **false**

$$lwork = \max(2 \times (\mathbf{n} - 1), 2) \quad \text{when } \mathbf{ncolb} = 0$$

$$lwork = \max(3 \times (\mathbf{n} - 1), 2) \quad \text{when } \mathbf{ncolb} > 0$$

**m** < **n**

**wantq** = **true** and **wantp** = **true**

$$lwork = \max(\mathbf{m}^2 + 5 \times (\mathbf{m} - 1), 2)$$

**wantq** = **true** and **wantp** = **false**

$$lwork = \max(3 \times (\mathbf{m} - 1), 1)$$

**wantq** = **false** and **wantp** = **true**

$$lwork = \max(\mathbf{m}^2 + 3 \times (\mathbf{m} - 1), 2) \quad \text{when } \mathbf{ncolb} = 0$$

$$lwork = \max(\mathbf{m}^2 + 5 \times (\mathbf{m} - 1), 2) \quad \text{when } \mathbf{ncolb} > 0$$

**wantq** = **false** and **wantp** = **false**

$$lwork = \max(2 \times (\mathbf{m} - 1), 1) \quad \text{when } \mathbf{ncolb} = 0$$

$$lwork = \max(3 \times (\mathbf{m} - 1), 1) \quad \text{when } \mathbf{ncolb} > 0$$

**work**( $\min(\mathbf{m}, \mathbf{n})$ ) contains the total number of iterations taken by the *QR* algorithm.

The rest of the array is used as workspace.

7: **ifail – int32 scalar**

0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

Errors or warnings detected by the function:

**ifail** = −1

One or more of the following conditions hold:

**m** < 0;

**n** < 0;

**lda** < **m**;

**ncolb** < 0;

**ldb** < **m** and **ncolb** > 0;

**ldq** < **m** and **m** < **n** and **wantq** = **true**;

**ldpt** < **n** and **m**  $\geq$  **n** and **wantq** = **true**, and **wantp** = **true**.

**ifail** > 0

The *QR* algorithm has failed to converge in  $50 \times \min(m, n)$  iterations. In this case **sv**(1), **sv**(2), ..., **sv**(**ifail**) may not have been found correctly and the remaining singular values may not be the smallest. The matrix  $A$  will nevertheless have been factorized as  $A = QEP^T$ , where the leading  $\min(m, n)$  by  $\min(m, n)$  part of  $E$  is a bidiagonal matrix with **sv**(1), **sv**(2), ..., **sv**( $\min(m, n)$ ) as the diagonal elements and **work**(1), **work**(2), ..., **work**( $\min(m, n) - 1$ ) as the superdiagonal elements.

This failure is not likely to occur.

## 7 Accuracy

The computed factors  $Q$ ,  $D$  and  $P$  satisfy the relation

$$QDP^T = A + E,$$

where

$$\|E\| \leq c\epsilon\|A\|,$$

$\epsilon$  is the *machine precision*,  $c$  is a modest function of  $m$  and  $n$  and  $\|\cdot\|$  denotes the spectral (two) norm. Note that  $\|A\| = sv_1$ .

## 8 Further Comments

>Following the use of f02we the rank of  $A$  may be estimated as follows:

```
tol = eps;
irank = 1;
while (irank <= numel(sv) && sv(irank) >= tol*sv(1) )
    irank = irank + 1;
end
```

returns the value  $k$  in **irank**, where  $k$  is the smallest integer for which **sv**( $k$ ) <  $tol \times \mathbf{sv}(1)$ , where  $tol$  is typically the machine precision, so that **irank** is an estimate of the rank of  $S$  and thus also of  $A$ .

## 9 Example

```
a = [2, 2.5, 2.5;
     2, 2.5, 2.5;
     1.6, -0.4, 2.8;
     2, -0.5, 0.5;
     1.2, -0.3, -2.9];
b = [1.1; 0.9; 0.6; 0; -0.8];
wantq = true;
wantp = true;
[aOut, bOut, q, sv, pt, work, ifail] = f02we(a, b, wantq, wantp)
```

```
aOut =
    0.6011    -0.1961    -0.3165
    0.6011    -0.1961    -0.3165
    0.4166     0.1569     0.6941
    0.1688    -0.3922     0.5636
   -0.2742    -0.8629     0.0139
bOut =
    1.6716
    0.3922
   -0.2276
   -0.1000
   -0.1000
q =
     0     0     0     0     0
sv =
```

```
        6.5616
        3.0000
        2.4384
pt =
    0.4694    0.4324    0.7699
   -0.7845   -0.1961    0.5883
    0.4054   -0.8801    0.2471
work =
    0.0000
    0.0000
    5.0000
    0.5883
   -0.1961
   -0.7845
   -0.2471
    0.8801
   -0.4054
    0.0000
    0.0000
    5.0000
   -0.3000
    0.3000
    0.8000
    1.0000
    1.0000
    0.0008
    0.0000
ifail =
        0
```

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